CLAIMS

1 1. A method of locating and displaying an image of a
2 target, the method comprising the steps of:
3   sensing a triggering event generated by a human
4 operator;
5   receiving information that characterizes at least one
6 machine-sensible feature of a target, said receiving step
7 occurring substantially simultaneously with said sensing
8 step; and
9   aiming a camera responsive to results of said sensing
10 and/or said receiving step.

11 2. The method of claim 1, wherein said sensing step
12 includes sensing a gesture of a human operator indicating a
13 target.

1 3. The method of claim 2, wherein said sensing step
2 includes sensing a gesture indicting a direction.

1 4. The method of claim 1, wherein said receiving step
2 includes receiving speech from said human operator.

1 5. The method of claim 4, wherein said sensing step
2 includes sensing a gesture indicting a direction.

1 6. The method of claim 4, further including processing
2 said speech for use with at least one machine sensor, said
3 at least one machine sensor and said speech assisting in
4 locating said target.

1 7. The method of claim 6, wherein said sensing step
2 includes sensing a gesture indicting a direction from said
3 human operator to said target.

1 8. The method of claim 6, wherein said processing step
2 includes processing said voice information through a look-

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3   up table corresponding said speech to search criteria for

4   use with at said least one sensor.

1   9. The method of claim 8, wherein said look-up table is

2   modifiable.

1   10.   The method of claim 9, wherein said look-up table

2   is modified by receiving information through the on-line

3   global computer network.

1   11.   The method of claim 9, wherein said look-up table

2   is modified to include an additional voice input and a

3   corresponding search criteria, said added voice input and

4   said corresponding search criteria established by comparing

5   previous association of said added voice input with at

6   least one machine sensible characteristic of at least one

7   correctly identified target associated with said voice

8   input, said machine sensible characteristic being a basis

9   for determining said corresponding search criteria.

1   12.   A method of locating and displaying an image of a

2   target, the method comprising the steps of:

3   scanning an area within the range of at least one

4   sensor;

5   identifying potential targets;

6   storing information concerning machine sensible

7   characteristics and locations of said possible targets;

8   sensing a triggering event, said triggering event

9   generated by a human operator;

10   receiving information that characterizes at least one

11   feature of said target, said receiving step occurring

12   substantially simultaneously with said sensing step; and

13   aiming a camera responsive to results of said sensing,

14   storing and/or said receiving steps.

1   13.   A method of aiming a camera at a target,

2 comprising the steps of:

3   inputting an indication of a position of a target;

4   inputting further information about a machine-sensible

5 characteristic of said target;

6   aiming a camera at said target responsively to said

7 indication using said further information to reduce an

8 error in said aiming.

1   14.   A method of acquiring a target, comprising the

2 steps of:

3   inputting spatial information to indicate a position

4 of a target;

5   inputting further information about said target; and

6   orienting an instrument with respect to said target to

7 acquire said target responsively to said spatial

8 information while using said further information to reduce

9 an ambiguity in said position.

1   15.   A method as in claim 14, wherein said step of

2 orienting includes orienting a camera.

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